



Standard Guide for Materials Handling Equipment for Hot Cells¹

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1. Scope

1.1 Intent:

1.1.1 This guide covers materials handling equipment used in hot cells (shielded cells) for the processing and handling of nuclear and radioactive materials. The intent of this guide is to aid in the selection and design of materials handling equipment for hot cells in order to minimize equipment failures and maximize the equipment utility.

1.1.2 It is intended that this guide record the principles and caveats that experience has shown to be essential to the design, fabrication, installation, maintenance, repair, replacement, and decontamination and decommissioning of materials handling equipment capable of meeting the stringent demands of operating, dependably and safely, in a hot cell environment where operator visibility is limited due to the radiation exposure hazards.

1.1.3 This guide may apply to materials handling equipment in other radioactive remotely operated facilities such as suited entry repair areas and canyons, but does not apply to materials handling equipment used in commercial power reactors.

1.1.4 This guide covers mechanical master-slave manipulators and electro-mechanical manipulators, but does not cover electro-hydraulic manipulators.

1.2 Applicability:

1.2.1 This guide is intended to be applicable to equipment used under one or more of the following conditions:

1.2.1.1 The materials handled or processed constitute a significant radiation hazard to man or to the environment.

1.2.1.2 The equipment will generally be used over a long-term life cycle (for example, in excess of two years), but equipment intended for use over a shorter life cycle is not excluded.

1.2.1.3 The equipment can neither be accessed directly for purposes of operation or maintenance, nor can the equipment be viewed directly, e.g., without shielded viewing windows, periscopes, or a video monitoring system.

1.3 User Caveats:

1.3.1 This standard is not a substitute for applied engineering skills, proven practices and experience. Its purpose is to provide guidance.

1.3.1.1 The guidance set forth in this standard relating to design of equipment is intended only to alert designers and engineers to those features, conditions, and procedures that have been found necessary or highly desirable to the design, selection, operation and maintenance of reliable materials handling equipment for the subject service conditions.

1.3.1.2 The guidance set forth results from discoveries of conditions, practices, features, or lack of features that were found to be sources of operational or maintenance problems, or causes of failure.

1.3.2 This standard does not supersede federal and/or state regulations, or codes applicable to equipment under any conditions.

1.3.3 This standard does not cover design features of the hot cell, e.g., windows, drains, and shield plugs. This standard does not cover pneumatic or hydraulic systems. Refer to Guides C 1533, C 1217, and ANS Design Guides for Radioactive Material Handling Facilities & Equipment for information and references to design features of the hot cell and other hot cell equipment.

1.3.4 *This standard does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety and health practices, and determine the applicability of regulatory limitations prior to use.*

2. Referenced Documents

2.1 *Industry and National Consensus Standards*—Nationally recognized industry and consensus standards applicable in whole or in part to the design, fabrication, and installation of equipment are referenced throughout this guide and include, but are not limited to, the following:

2.2 *ASTM Standards*:²

C 859 Terminology Relating to Nuclear Materials³

C 1217 Guide for Design of Equipment for Processing Nuclear and Radioactive Materials³

C 1533 Guide for General Design Considerations for Hot Cell Equipment³

2.3 *Other Standards*:

² For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

³ *Annual Book of ASTM Standards*, Vol 12.01.

¹ This guide is under the jurisdiction of ASTM Committee C26 on Nuclear Fuel Cycle and is the direct responsibility of Subcommittee C26.14 on Remote Systems. Current edition approved July 10, 2003. Published August 2003.

AAI A14.3 Ladders, Fixed Safety Requirements, OSHA⁴
 ANS 8.1 Nuclear Criticality Safety in Operations with Fissile Materials Outside Reactors⁵
 ANS Design Guides for Radioactive Material Handling Facilities & Equipment, ISBN: 0-89448-554-7⁵
 ASSE SA/SAFE Ladders, Fixed Safety Requirements, OSHA⁵
 ANSI B30.2 Overhead and Gantry Cranes⁶
 ASME NQA 1 Quality Assurance Requirements for Nuclear Facility Applications⁷
 ASME NOG-1 Rules for Construction of Overhead Gantry Cranes (Top-Running Bridge, Multiple Girder)⁷
 ISO/TC 85/SC 2 N 637 E Remote Handling Devices for Radioactive Materials—Part 1 : General Requirements⁸
 ISO 9001 Quality Management Systems Requirements⁸
 NEMA 250 Enclosures for Electrical Equipment 1000 Volts Maximum (Type 4)⁹
 NFPA 70 National Electric Code¹⁰

2.4 Federal Regulations:

10CFR50 Appendix B, Quality Assurance¹¹
 10CFR830.120 Nuclear Safety Management Quality Assurance Requirements¹¹
 29CFR1910 Occupational Safety and Health Standards¹¹
 40CFR 260-279 Solid Waste Regulations¹¹

3. Terminology

3.1 Definitions:

3.1.1 The terminology employed in this guide conforms with industry practice insofar as practicable.

3.1.2 For definitions of general terms used to describe hot cells and hot cell equipment, refer to Terminology C 859, and Guide C 1533.

3.1.3 *bogie*—a bogie is a small cart used to move material, supplies and small tools into, out of and within a hot cell.

3.1.4 *boot*—boot in this context refers to a flexible covering over equipment including a manipulator to protect it from radioactive contamination. The boot may also protect the equipment or manipulator from acid, caustic solutions and abrasive powders.

3.1.5 *Cartesian coordinate system*—a three-dimensional coordinate system in which the coordinates of a point in space are its distances from each of three intersecting, mutually perpendicular, planes along lines parallel to the intersection of the other two. Usually referred to as X, Y, and Z.

3.1.6 *coordinated control*—control of a manipulator that allows multiple axes of the manipulator to be automatically controlled to achieve a special motion of the wrist or end effector. These motions can be straight-line motion of the wrist or end effector, rotation about a point, movement in Cartesian coordinates or other motions at the wrist or end effector requiring relative motion of more than one joint.

3.1.7 *deadhead*—the act of placing a force on an immovable object or component.

3.1.8 *electro-hydraulic manipulator*—a manipulator in which each joint, either rotary or linear, of an electro-hydraulic manipulator is operated by a hydraulic motor or hydraulic cylinder. Control of the flow of hydraulic fluid to the hydraulic motors or cylinders to control position and speed are by electric-controlled servo valves. Electro-hydraulic manipulators are primarily used in under-sea environments and are generally not used in hot cells to date.

3.1.9 *electro-mechanical manipulator*—a manipulator in which each joint, either rotary or linear, of the electro-mechanical manipulator (E/M) is operated by an electric motor or electric actuator. The E/M is usually mounted on a crane bridge, wall, pedestal or ceiling and is used to handle heavy equipment in a hot cell. The E/M is operated remotely using controls from the uncontaminated side of the hot cell.

3.1.10 *end effector*—an end effector is a gripper or other device or tool on the end (wrist) of a slave of a master-slave or power manipulator.

3.1.11 *force ball*—a force ball is an input device in the shape of a sphere that provides signals relative to force and/or torques placed on the ball by an operator. The signals are usually segregated into forces and torques in different directions, usually Cartesian, even though the operator input is generally in a combination of directions.

3.1.12 *force control*—force control is automated control or computer control of a manipulator to maintain a certain force or range of forces on an end effector. Force control requires a sensor to monitor the force or force/torque at the end effector to allow automated or computer control.

3.1.13 *force feedback*—force feedback is an electrical signal relative to force sensed, usually at a joint of a manipulator. Force feedback is commonly used to generate a force at the master that is relative to the sensed force on the end effector.

3.1.14 *force reflection*—force reflection is the perception of force at the master of a master/slave manipulator that is relative to the forces applied at the end effector.

3.1.15 *gray*—the SI unit of absorbed radiation dose. One Gray (Gy) equals 100 Rads.

3.1.16 *hot cell*—a hot cell is an isolated, shielded room that provides a controlled environment for containing highly radioactive and contaminated material and equipment. The radiation levels within a hot cell are typically several grays or more per hour (hundreds of Rads per hour). See Guide C 1533 for more detail.

3.1.17 *mechanical master-slave manipulator*—a mechanical master-slave (m/s) manipulator is a device used to remotely handle materials in a hot cell. It replicates the actions of an

⁴ Available from U.S. Government Printing Office, Superintendent of Documents, Mail Stop SSOP, Washington, DC 20402-9328

⁵ Available from American Nuclear Society, 555 North Kensington Ave., La Grange Park, IL 60525, (312) 352-6611

⁶ Available from American National Standards Institute, 11 W. 42nd St., 13th Fl., New York, NY 10036

⁷ Available from American Society of Mechanical Engineers, 3 Park Ave., New York, NY 10016

⁸ Available from International Organization for Standardization (ISO), 1 rue de Verembe, Case postale 56, CH 1211, Geneva 20, Switzerland

⁹ Available from Global Engineering Co., 15 Inverness Way, Englewood, CO 80112

¹⁰ Available from National Fire Protection Agency (NFPA), One Batterymarch Park, Quincy, MA 02269

¹¹ Available from U.S. Government Printing Office, Superintendent of Documents, Mail Stop SSOP, Washington, DC 20402-9328

operator outside the cell with a manipulator in the cell by means of a mechanical connection between the two, usually a metal tape or cable.

3.1.18 *mock up*—an area designated for the testing of hot cell equipment or the process of qualifying said equipment prior to sending it into the hot cell for operation. A mockup is usually equipped with master-slave manipulators and electro-mechanical manipulators and cranes to simulate the hot cell dimensional envelope and operations.

3.1.19 *moused hook*—a moused hook is a lifting hook on a crane that has a latch (mouse) across the mouth of the hook. The latch keeps the cable, bail or other device within the hook so that it can not accidentally slide off of the hook. The latch is manually activated to release the cable, bail or other device from the hook. Moused hooks are not used in hot cells because of the inability to manually release the latch.

3.1.20 *pendant*—a pendant is a box with switches, buttons, other controls and sometimes a small display screen used to control equipment including manipulators and cranes. The pendant usually has a cable or umbilical cord to transmit signals from and to the pendant. Some pendants transmit and receive signals over radio frequencies, so they don't require an umbilical cord.

3.1.21 *power manipulator*—a manipulator with joints activated electrically or hydraulically. See electro-hydraulic manipulator and electro-mechanical manipulator.

3.1.22 *teleoperated control*—teleoperated control is remote control of equipment, including manipulators and cranes by an operator from outside the hot cell or confinement. Teleoperated control is aided by an operator's view of the equipment through a window, periscope or camera/monitor. An operator is always "in-the-loop" in teleoperated control.

3.1.23 *through-the-wall sleeve*—a through-the-wall sleeve is a pipe, open at both ends, embedded in the shield wall of a hot cell into which the manipulator is inserted. A window is generally placed below the sleeve(s) to provide the operator a view of the manipulator(s).

4. Significance and Use

4.1 Materials handling equipment operability and long-term integrity are concerns that originate during the design and fabrication sequences. Such concerns are most efficiently addressed during one or the other of these stages. Equipment operability and integrity can be compromised during handling and installation sequences. For this reason, the subject equipment should be handled and installed under closely controlled and supervised conditions.

4.2 This guide is intended as a supplement to other standards (Section 2, Referenced Documents), and to federal and state regulations, codes, and criteria applicable to the design of equipment intended for this use.

4.3 This guide is intended to be generic and to apply to a wide range of types and configurations of materials handling equipment.

4.4 The term *materials handling equipment* is used herein in a generic sense. It includes manipulators, cranes, carts or bogies, and special equipment for handling tools and material in hot cells.

4.5 This service imposes stringent requirements on the quality and the integrity of the equipment, as follows:

4.5.1 Boots and similar protective covers should not restrict movement of the equipment, should be properly sealed to the equipment and should withstand the radiation, cell atmosphere, dust, cell temperatures, chemical exposures, and cleaning and decontamination reagents, and also resist snags and tearing.

4.5.2 Materials handling equipment should be capable of withstanding rigorous chemical cleaning and decontamination procedures.

4.5.3 Materials handling equipment should be designed and fabricated to remain dimensionally stable throughout its life cycle.

4.5.4 Attention to fabrication tolerances is necessary to allow the proper fit-up between components for the proper installation and mounting of materials handling equipment in hot cells, for example, when parts or components are being replaced. Fabrication tolerances should be controlled to provide sufficiently loose fits where possible to aid in remote maintenance and replacement of equipment and components.

4.5.5 Fabrication materials should be resistant to radiation damage, or materials subject to such damage should be shielded or placed and attached so as to be readily replaceable.

4.5.6 Smooth surface finishes are necessary for decontamination reasons. Irregularities that hide and retain radioactive particulates or other adherent contamination should be eliminated or minimized.

4.6 Materials handling equipment that is exposed to high temperatures, pressures, acidic or caustic conditions may require special design considerations to be compatible with the operating environment. Potential rates of change for temperature and pressure as well as absolute temperature and pressure extremes, created by activation of fire suppression systems and other emergency systems, should be considered.

4.7 When replacing, modifying or adding additional materials handling equipment to an existing hot cell, maintenance records of materials handling equipment in that hot cell or in a hot cell having a similar processing mission may be available for reference. These records may offer valuable insight with regard to the causes, frequency, and type of failure experienced for the type and class of equipment being designed and engineered, so that improvements can be made in the new equipment.

4.8 Preventive maintenance based on previous experience in similar environments and similar duty should be performed to prevent unscheduled repair of failed components.

5. Quality Assurance and Quality Requirements

5.1 The owner-operator should administer a quality assurance program approved by the agency of jurisdiction. QA programs may be required to comply with 10CFR50 Appendix B, 10CFR830.120 Subpart A, ASME NQA-1, or ISO 9001.

5.2 The owner-operator should require appropriate quality assurance of purchased materials handling equipment and components to assure proper fit up, operation and reliability of the equipment in the hot cell.

6. General Requirements

6.1 *Design Caveat:*